



Using image analysis to monitor cow (and calf) fitness'

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Introduction

Monitoring of dairy cows and their calf during parturition is essential in determining if there are any associated problems for mother and offspring and whether or not there is a need for human intervention, which can be dangerous for stockperson. Behavioural changes, such as standing or lying bouts, can give an indication to whether there is a need for assistance.

Current automated devices

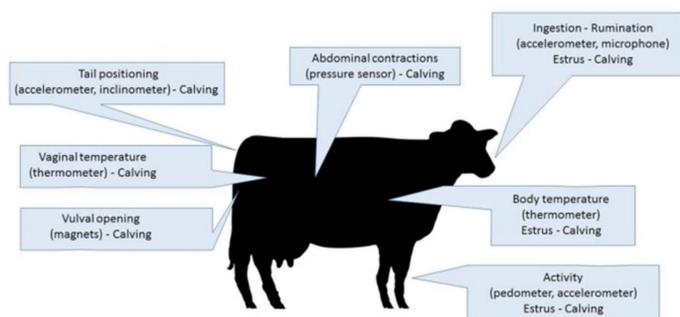


Fig 1. Types of automated devices that are currently used for monitoring calving Source: Saint-Diziera and Chastant-Maillard, 2018.

The dairy farming industry currently uses four different types of automated devices for monitoring calving detection (Fig 1) **all of which are invasive to the cow**

Benefits of using image analysis

- Does not need to rely on transponder attachments or invasive tools
- Provides more information at a relatively low cost
- Uses existing video surveillance
- Can detect and track the new born calf
- Possible to identify rare behavioural patterns or behaviours

New behaviour dataset

A new dataset for the purpose of detecting behaviour changes in cows.

- 46 calving's are recorded (10 hours before and 5 hours after parturition).
- 9 categories (Table 1) are annotated
- Around 1,000 videos (10 seconds clips) in each category.
- Total of 33 hours for training and 2.5 hours for testing/evaluation

| State 1 (Posture) | State 2 (Behaviour) | Events (Behaviour) | Events (Parturition) |
|-------------------|---------------------|-------------------------------|----------------------|
| Stand | Eating | Contractions (lying/standing) | Birth |
| Lie | Drinking | | |
| Walk | | | |
| Shuffle | | | |

Table 1. Behavioural state and events to be recorded around parturition for each cow.

Object detection

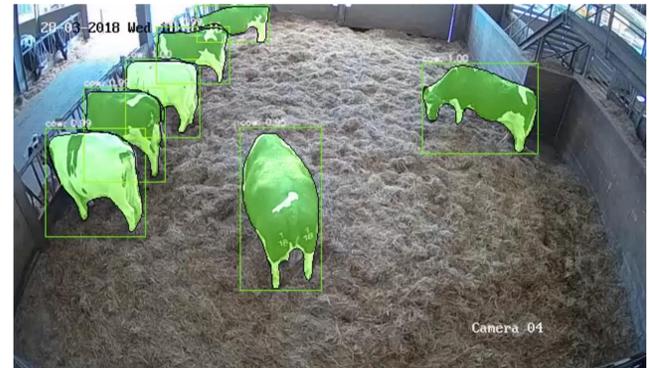


Fig 2. Video surveillance at Sutton Bonington Dairy Centre. Masks are shown in colour, bounding boxes, category and confidence scores are also displayed.

Object detection and instance segmentation (Fig 2) is accomplished using the state-of-the-art Mask R-CNN (He *et al.* 2017), trained on the MS COCO (Lin *et al.* 2015) dataset.

- We use Resnet-50 (He *et al.* 2015) as the backbone architecture.
- To improve detection in different scales we use a Feature pyramid network (Yin *et al.* 2017).
- Further improvements to detection/segmentation are achieved using a Non-local block (Wang *et al.* 2018) and group normalisation (Wu and He, 2018).

Behaviour Classification

To predict animal behaviour, we use a Non-Local Neural network (Wang *et al.* 2018) with 9 behaviour categories, (Fig 3).

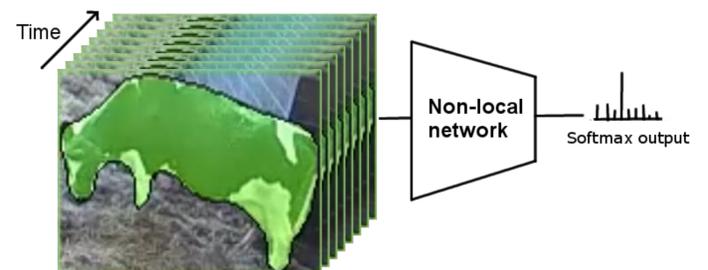


Fig 3. Eight evenly spaced frames are passed through the non-local network, a softmax layer is used to predict the behaviour category.

References

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